

## **PRE-INFORMATION**

# ROTARY SWIVEL LINEAR HEAD RSLH35T for fiber laser



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#### 1 GENERAL INFORMATION

#### 1.1 Pre-information

This pre-information gives you an overview about the main functions and main components of our *Rotary-Swivel-Linear-axis Laser Head RSLH35T* and describes the interfaces and needs to plan the integration into your laser machine.

#### 1.2 Legal provisions

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#### 1.3 Use for intended purpose

The RSLH35T is a laser beam guidance product with three motorized axis and has been designed and developed to be mounted in a fiber laser machine for 3D laser applications ( $\lambda = 1030-1080 \text{ nm}$ ), like cutting of deep-drawn parts or other three-dimensional profiles.

### 1.4 Product description

The RSLH35T laser head consists primarily of three main units made from LT-Ultra

- a collimator unit to collimate the expanded laser light coming from the laser fiber
- a multi-axis drive unit with three torque motors to enable 3D movement, including a
  fast linear axis for compensatory movements, and two mirrors to guide the collimated
  laser light to the cutting unit
- a *focusing* unit to focus the laser light for cutting applications

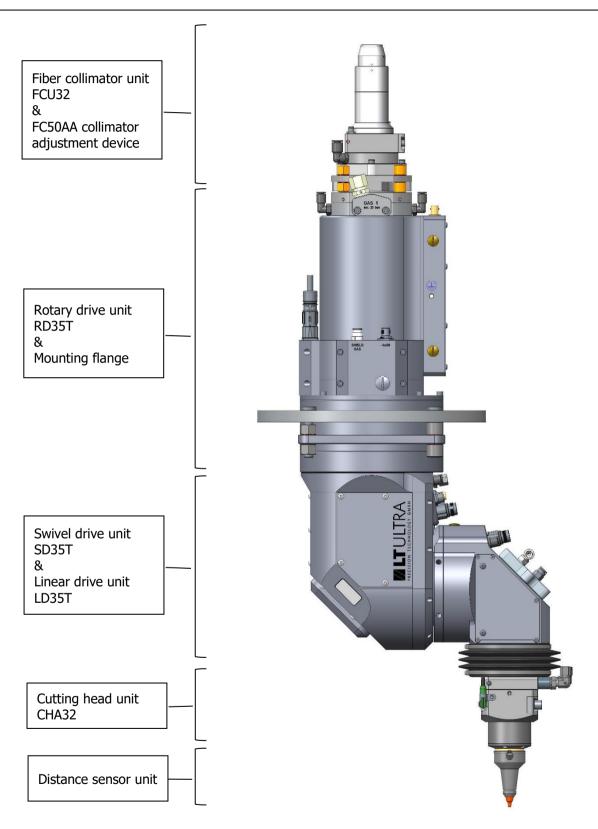
The laser head is prepared to mount a distance sensor system with M30 x 1 mm interface and pre-amplifier. Ask our sales department for this optional add-on part.

To set the focus position relative to the nozzle tip we use an adaptive mirror (pneumatically deformable mirror) instead of a moved lens in the CHA cutting unit.

Water-cooled torque motors and laser head components enable the laser head to operate for high dynamic applications and high laser power.

The linear axis drive is designed to enable a high dynamic distance regulation between work piece and laser cutting nozzle.





RSLH35T laser head (with optional distance sensor):



## 1.5 Axis designations

endless rotary axis = <b>C-axis</b>	swivel axis = <b>A-axis</b>	linear axis = <b>Z-axis</b>
charge retaily artic		

#### 1.6 Functional tests

All mechanical and electrical functions of this product have been tested at our Siemens SINUMERIK 840D SL test stand. These function tests include various positioning tests and an endurance test for some hours. The reports are attached to the delivery.

### 1.7 Product training

We recommend attending a product training in our company before you make the first installation of one of our 3D laser heads. We focus out the main subjects of the operating manual and have the possibility to discuss customized subjects. This training will provide you practical and theoretical information for your work with the laser head.



# 1.8 Data overview

Fiber connector mount	QB or QD
Focusing lengths	<ul> <li>collimator FCU32: CL 80, 100 (standard), 120 mm</li> <li>cutting unit CHA32: FL 120, 150 (standard), 200 mm</li> </ul>
Focus movement range	10 up to 40 mm (depending on FL of CHA32)
Mechanical aperture	32 mm (limited by collimator and cutting unit)
Media connectors	<ul> <li>Water IN / OUT (cooling water max. 6 bar)</li> <li>LEAKAGE (feed-through inspection tube; always open)</li> <li>GAS I (gas line max. 25 bar)</li> <li>GAS II (gas line max. 10 bar)</li> <li>SHIELD GAS (optional use)</li> <li>BRAKE (gas line max. 8 bar)</li> <li>AD/AM (gas line max. 8 bar)</li> <li>pressure sensors for GAS I and AM optional on request</li> </ul>
Mirror optics	<ul><li>FMU-E401 flat mirror unit (not adjustable)</li><li>AM-E501 adaptive mirror unit (adjustable)</li></ul>
Installation	Horizontal (Levelling device ± 1,25°)
Rotary axis (C)	<ul> <li>rotation range: endless</li> <li>max. speed: 120 1/min *)</li> <li>max. acceleration: 20 1/s² *)</li> <li>torque motor 420 V<sub>AC</sub></li> <li>measuring system: absolute</li> </ul>
Swivel axis (A)	<ul> <li>swivel range: approx. ± 135°</li> <li>max. speed: 120 1/min *)</li> <li>max. acceleration: 30 1/s² *)</li> <li>torque motor 230 V<sub>AC</sub></li> <li>brake: pneumatic (min. 6 bar)</li> <li>measuring system: absolute</li> </ul>
Linear axis (Z)	<ul> <li>linear range: ± 10 mm</li> <li>max. speed: 20 1/min *)</li> <li>max. acceleration: &gt;2.5 G *)</li> <li>torque motor 230 V<sub>AC</sub></li> <li>measuring system: absolute</li> </ul>
Safety elements	<ul> <li>protection glass collimator</li> <li>collision safety clutch</li> <li>protection glass cutting unit</li> </ul>
Water cooled elements	<ul> <li>torque motors (SS, anodized AL)</li> <li>lens holders and mirrors (SS, CU)</li> <li>housing parts (SS, anodized AL)</li> </ul>
Weight	• ∼35 kg
Storage temperature	• - 15° C to + 50° C, short time + 60°C ( 24h)
Environmental conditions	• temperature 10°C to + 45°C / humidity < 80%



#### 2 LASER HEAD COMPONENTS

#### 2.1 Fiber collimator unit FCU32

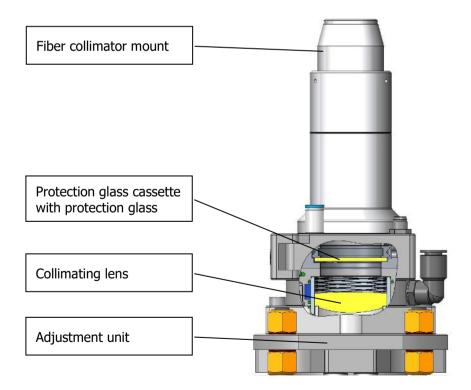
To connect your laser fiber with the laser head you can choose between a QB and a QD mount version. In the picture below, you see the common QB mount.

For best optical performance, we use an aspherical lens to collimate the laser beam. Depending on your laser application, you can choose between focal length 80, 100 or 120 mm. The maximum mechanical aperture of the beam path is 32 mm.

Between fiber mount and lens, is a protection glass ( $\emptyset$  38 x 2 mm) which helps to avoid that particles or dust contaminates the collimating lens especially while plugging or unplugging the laser fiber. The protection glass is in a removable cassette to enable an easy visual check and change. An inductive sensor control if the cassette is in or not.

A PT1000 temperature sensor measure the temperature in the collimator housing.

The collimator is to connect to a water cooling circuit to cool the holder of the collimating lens. As all other water-cooled components of the laser head, the connection is in line, never parallel.



FCU32 collimator (QB) & FC50AA adjustment unit:



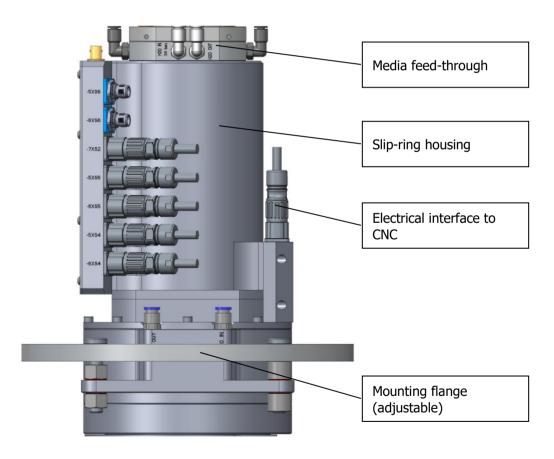
#### 2.2 Adjustment unit FC50AA

This unit allows adjusting the collimator, respectively the laser beam in both main directions to the Rotary-C-axis. After fixing the screws, this unit hold the collimator in a defined and stiff way.

#### 2.3 Rotary drive unit RD35T - C-axis

The mechanical interface to your laser machine is the mounting flange at the RD35T housing. In the standard version, this flange is adjustable.

For the rotary drive, we use a modern, backlash-free, high performance torque motor technology, that assures good dynamics and high precision. The motor is water cooled and equipped with a KTY and PTC temperature sensor.



RD35T rotary unit:

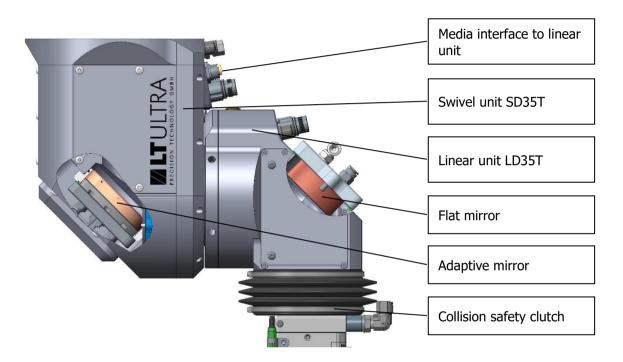
To enable the RD35T unit to rotate endless, this unit contains a media feed-through and a slip-ring for all electrical lines from swivel and linear axis.



#### 2.4 Swivel drive unit SD35T - A-axis

For the swivel drive, we use the same torque motor technology as for the rotary axis. The motor is water cooled and equipped with a KTY and PTC temperature sensor.

In the standard version, the swivel axis is equipped with a brake. To open the brake you need compressed air (cleaned according to FESTO valve specification) of minimum 6 bar.



SD35T swivel & LD35T linear unit:

The adaptive mirror (AM) is mounted in the bottom of the SD35T unit. The mounting plate of the AM is adjustable.

The second mirror is the flat mirror. It's mounted in the swivel housing in a fixed position with defined reference surfaces. Precisely manufactured mirror fixing points speed up the restart of your laser machine after a mirror change.

Both mirrors are water-cooled.

#### 2.5 Linear drive unit LD35T - Z-axis

For the linear drive, we use the same torque motor technology as for the rotary and swivel axis. The motor is water cooled and equipped with a KTY and PTC temperature sensor.

A tooth belt transforms the rotary in a linear movement.



#### 2.6 Collision safety clutch

The bottom interface flange of the linear axis is designed as a collision safety clutch which reduce the risk that laser head and other laser machine components get damaged irreversible in case of a lateral or axial collision with the laser head tip.

In case of a lateral collision the CHA-unit can swing out some degrees in all directions or in case of an axial collision can move some less millimetres into the laser head. The newest collision clutch design has direct electrical contacts so that even the smallest tilting of the CHA-unit will interrupt the electrical line to your CNC immediately.

The clutch flange will move back automatically in the straight 0° position after the collision.

#### 2.7 Adaptive mirror

With the adaptive mirror technology, you shift the focus position up and down pneumatically, while the lens is always in a fixed position. The pressurized rear of the adaptive mirror deform the mirror surface and shift the focus position in a defined way. The little variation of the beam diameter is normally not significant.

Lower pressure shift the focus up, higher pressure shift the focus down. The relationship between pressure and focus shift is nearly linear.

The total possible focus shift is limited by the focal length of the CHA32 unit. Typical values you see in the table below. This information is without considering mechanical and optical tolerances.

	max. pressure Adaptive Mirror (AM) 6 bar 8 bar					
Focal length CHA	Focal length CHA 6 bar					
120 mm	11 mm	15 mm				
150 mm	18 mm	24 mm				
200 mm	32 mm	44 mm				

The focus shift range is separated in a "focus +" part (focus is positioned above the material like for an oxygen cut) and in a "focus -" part (focus is positioned below the material surface like for a nitrogen high pressure cut).

If you use our longer adapter to mount the distance sensor or if you use your own longer cutting nozzles, you can customize the "focus +" part.

To complete the adaptive mirror technology we deliver a 6 bar or optional 8 bar high precision pneumatic servo valve.



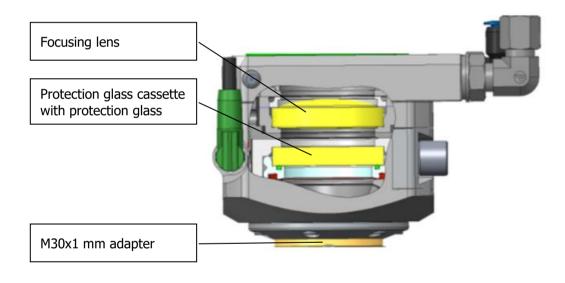
#### 2.8 Cutting head unit CHA32

For best optical performance, we use an aspherical lens to focus the laser beam. Depending on your laser application, you can choose between focal length 120, 150 or 200 mm. The maximum mechanical aperture of the beam path is 32 mm.

The protection glass ( $\emptyset$  1,5" x 0,250") below the lens has two functions. It seals the pressure chamber to the laser head and it protect the lens from sparks during the laser process. The protection glass is in a removable cassette to enable an easy visual check and change. An inductive sensor control if the cassette is in or not.

A PT1000 temperature sensor measure the temperature in the CHA housing.

The CHA unit is to connect in line (not parallel) to the cooling water circuit.



CHA32 cutting unit:

#### 2.9 Distance sensor unit

The cutting head unit CHA has an M30x1 thread interface to mount for example a Precitec distance sensor system in KN or KS version. Such a system is an optional add-on part to complete the laser head.

Note! We refer to Precite for service and all questions on functions and needs to use a Precite distance sensor system in combination with your laser machine.



#### 3 MOTOR DRIVES

### 3.1 Motor power supply

For this laser head construction, we use **3-phase synchronous frameless torque** motors. Note the different requirements for CNC motor drive hardware.

Motor rotary C-axis: 420 V<sub>AC</sub> (600 V<sub>dc</sub>)
 Motor swivel A-axis: 230 V<sub>AC</sub> (300 V<sub>dc</sub>)
 Motor linear Z-axis: 230 V<sub>AC</sub> (300 V<sub>dc</sub>)

## 3.2 Motor specifications - C-axis rotary drive

	Parameter	Remarks	Sym bol	Unit	Torque Motor C-Axis 753319
	Motor type Max. voltage ph-ph				3-phase synchronous frameless Torque 420Vacrms (600Vdc)
Performance	Peak Torque	motor temp. increase 6°C per second	Тр	Nm	58.3
rforr	Continuous Torque		Тс	Nm	(36.3) <b>*)</b>
P.	Maximum speed	@Tc	N <sub>max</sub>	rpm	(385) <b>**)</b>
	Motor Torque constant	up to I <sub>c</sub>	$K_{t}$	Nm/A <sub>rms</sub>	9.20
	Motor constant		Km	(Nm) <sub>2</sub> /W	2.29
	Peak Current		Ιp	Arms	7.4
	Maximum Continuous Current		Ic	Arms	(3.95) <b>*)</b>
	Back EMF Phase-Phasepeak		Ke	V/krpm	787
Electrical	Back EMF Phase-Phase <sub>RMS</sub>		Ke	V/krpm	556
Elect	Coil Resistance per Phase	coils @ 25°C ex. cable	R	Ω	12.3
	Coil induction per Phase		L	mH	47.9
	Electrical Time Constant	coils @ 25°C	$\tau_{\text{e}}$	ms	3.88
	Poles		N <sub>mgn</sub>	nr	36 (= 18 pole pairs)
	Continuous Power Loss	coils @ 100°C	Pc	W	750
Thermal	Thermal Time Constant	up to 63% max. coil temp. (100°C)	Τth	S	29
The	Motor Temperature safety sensor				PTC 1k $\Omega$ sensor
	Motor temperature monitoring				modified KTY sensor

All specifications ±10%

<sup>\*) @ 20°</sup>C motor temperature. For higher temperatures the continuous current and torque must be reduced.

<sup>\*\*)</sup> effective usable maximum speed is limited by laser head design



# 3.3 Motor specifications – A-axis swivel drive

	Parameter	Remarks	Sym bol	Unit	Torque Motor A-Axis 753577
	Motor type Max. voltage ph-ph				3-phase synchronous frameless Torque 230Vacrms (300Vdc)
Performance	Peak Torque	motor temp. increase 6°C per second	Тр	Nm	13.1
- Ju	Continuous Torque		Тс	Nm	(10) * <b>)</b>
- B	Maximum speed	@T <sub>c</sub>	N <sub>max</sub>	rpm	(910) ** <b>)</b>
	Motor Torque constant	up to I <sub>c</sub>	$K_{t}$	Nm/A <sub>rms</sub>	2.09
	Motor constant		Km	(Nm) <sub>2</sub> /W	0.344
	Peak Current		Iр	Arms	7.31
	Maximum Continuous Current		lc	Arms	(4.77) *)
	Back EMF Phase-Phase <sub>peak</sub>		Ke	V/krpm	179
Electrical	Back EMF Phase-Phase <sub>RMS</sub>		Ke	V/krpm	126
	Coil Resistance per Phase	coils @ 25°C ex. cable	R	Ω	4.23
	Coil induction per Phase		L	mH	11.5
	Electrical Time Constant	coils @ 25°C	Τe	ms	2.72
	Poles		N <sub>mgn</sub>	nr	28 (= 14 pole pairs)
	Continuous Power Loss	coils @ 100°C	Pc	W	375
Thermal	Thermal Time Constant	up to 63% max. coil temp. (100°C)	Tth	S	19
본	Motor Temperature safety sensor				PTC 1k $\Omega$ sensor
	Motor temperature monitoring				modified KTY sensor

All specifications ±10%

<sup>\*) @ 20°</sup>C motor temperature. For higher temperatures the continuous current and torque must be reduced.

<sup>\*\*)</sup> effective usable maximum speed is limited by laser head design



## 3.4 Motor specifications – Z-axis linear drive

	Parameter	Remarks	Sym bol	Unit	Torque Motor Z-Axis 753321
	Motor type Max. voltage ph-ph				3-phase synchronous frameless Torque 230Vacrms (300Vdc)
Performance	Peak Torque	motor temp. increase 6°C per second	Тр	Nm	3.9
rforr	Continuous Torque		Tc	Nm	(3.2) *)
Pe	Maximum speed	@Tc	Nmax	rpm	(3579) ** <b>)</b>
	Motor Torque constant	up to I <sub>c</sub>	Kt	Nm/A <sub>rms</sub>	0.595
	Motor constant		Km	(Nm) <sub>2</sub> /W	0.061
	Peak Current		Ιp	Arms	7.56
	Maximum Continuous Current		lc	Arms	(5.34) *)
	Back EMF Phase-Phasepeak		Ke	V/krpm	51
Electrical	Back EMF Phase-Phase <sub>RMS</sub>		Ke	V/krpm	36
Elect	Coil Resistance per Phase	coils @ 25°C ex. cable	R	Ω	1.93
	Coil induction per Phase		L	mH	4.05
	Electrical Time Constant	coils @ 25°C	Τe	ms	2.1
	Poles		Nmgn	nr	20 (= 10 pole pairs)
	Continuous Power Loss	coils @ 100°C	Pc	W	214
Thermal	Thermal Time Constant	up to 63% max. coil temp. (100°C)	Tth	S	16
The	Motor Temperature safety sensor				PTC 1k $\Omega$ sensor
	Motor temperature monitoring				modified KTY sensor

All specifications ±10%

#### 3.5 Motor temperature sensors

Each motor has two temperature sensors. A "*KTY"-sensor* to observe and monitor the current motor temperature and a "*PTC*"-sensor (1  $k\Omega$ ) for an automatically power switch-off in case of impermissible motor temperature.

#### 3.6 Measuring system

The axis of this laser head is equipped with an absolute angle encoder from Renishaw.

Type: <u>RESOLUTE™ absolute encoder system with RESA rotary (angle) ring</u>
The read heads are available in different versions for different CNC systems.

For example:

- Siemens DRIVE-CLiQ FS
- BiSS-C
- Fanuc
- YASKAWA

For more detailed information observe the data sheets on Renishaw homepage.

<sup>\*) @ 20°</sup>C motor temperature. For higher temperatures the continuous current and torque must be reduced.

<sup>\*\*)</sup> effective usable maximum speed is limited by laser head design



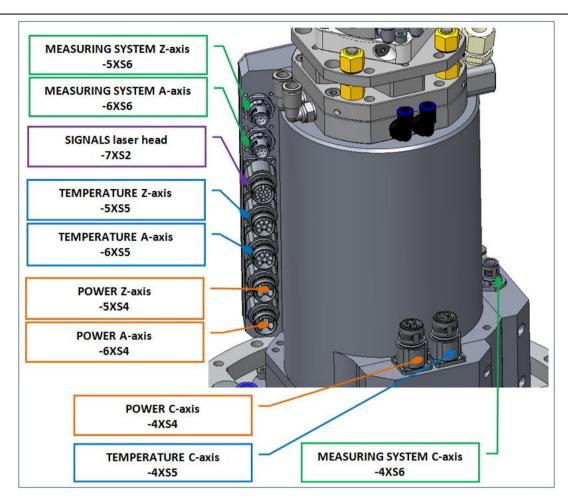
# 4 MEDIA INTERFACES

Media inter- face	Medium Operating pressure *)		Specifications	Fitting		
WATER IN WATER OUT	I Cooling water		Push-in Ø 8 mm			
LEAK Feed-through	Cooling water leakage	open hose		Push-in Ø 6 mm		
GAS I Cutting gas	l Process das l ≤ 25 bar l		Bolting (G1/4")			
G1/4"-thread (channel GAS I)	For optional sensor	≤ 25 bar	observe information in the manual	Locking screw (G1/4")		
GAS II (shield gas Z- axis)	Clean gas	< 1 bar		Push-in Ø 6 mm		
BRAKE A-axis	Compressed air	6 – 8 bar	in the mandar	Push-in Ø 6 mm		
AD/AM Adaptive mirror	Compressed air	≤ 8 bar		Push-in Ø 6 mm		
CLEAN GAS Collimator (optional)	Clean gas	~ 0.1 bar		Push-in Ø 6 mm		
SHIELD GAS (optional)	Clean gas	< 1 bar		Push-in Ø 6 mm		

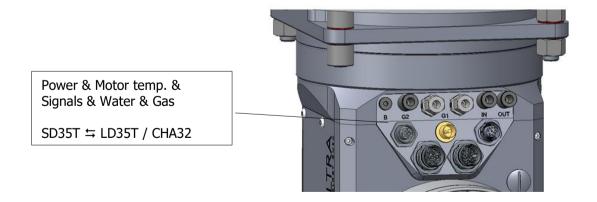
\*) static pressure

Overview gas and water connections:





### Electrical cabling to CNC:



Electrical cabling and media tubing to swivelled units:



	Connectors at RSLH35T laser head	Connectors at lengther	Connectors at lengthening cables for RSLH35T laser head
	POWER C,A,Z-axis - interface to lengthening cables	OWER C / A,Z-axis - inter	POWER C,A,Z-axis - interface to customer
Quantity Example	3 Phoenix Contact ST-3EP1N8AW400S (M17-SPEEDCON)	3 Phoenix Contact ST-3ES1N8A8K03S (M17-SPEEDCON)	3 LAPP EPIC® POWER LS1 F6 5+PE (M23)
terfaces and o			
Connector Quantity Example	TEMPERATUR C,A,Z-axis - interface to lengthening cables 3 Phoenix Contact ST-6EP1N8AW400S (M17)	TEMPERATUR C.A.Z-axis - interface to laser head 3 Phoenix Contact ST-6ES1N8A8004 (M17)	TEMPERATUR C,A,Z-axis - interface to customer 3 SIEMENS 6FX2003-0SA07 (M17)
Connector Quantity Example	MEASURING SYSTEM C,A,Z-axis - interface to lengthening cables 3 Phoenix Contact SACC-DSI-M12MS-8CON-M16 SH (M12-SEEDCON)	MEASURING SYSTEM C,A,Z-axis - interface to laser head 3 Phoenix Contact SACC-FS-8QO-0,5 SH SCO (M12-SEEDCON)	MEASURING SYSTEM C,A,Z-axis - interface to customer or Drive-CliQ-box 3 Phoenix Contact SACC-MS-8QO-0,5 SH SCO (M12-SEEDCON)
	6 6 6 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4	3 0 8 0 7	6 8 1 1 2 3 3 3 3 3 3 3 3 3 3 3 3 3 3 3 3 3
Connector Quantity Example	SIGNALS - interface to lengthening cables  1 Phoenix Contact ST-17P1N8AWQ00S (M17-SEEDCON)	SIGNALS - interface to laser head 1 Phoenix Contact ST-17SINBA8004S (M17-SEEDCON)	SIGNALS - interface to customer  1 Phoenix Contact CA-17P1N8A9007 (M23)
	17 13 1 2 3 1 14 10 10 10 10 10 10 10 10 10 10 10 10 10	3 2 1 13 13 13 14 14 14 15 15 15 15 15 15 15 15 15 15 15 15 15	N S S S S S S S S S S S S S S S S S S S

Electrical interfaces and cabling:



#### 5 **CONFIGURATION OVERVIEW**

Fiber connector

\*) QB: 232419

QD: 702624

Fiber collimator unit FCU32

\*) Protection glass 2 mm: 211258

Lens CL 80 mm: 211203 \*) Lens CL 100 mm: 211131

Lens CL 120 mm: 211195

## C-, A-, Z-axis Read head measuring system

\*) Siemens Fanuc **Biss** 

#### **Mirrors**

\*) Adaptive mirror: 211486

\*) Flat mirror: 211572

#### Cutting head unit CHA32

Lens FL 120 mm: 211195 \*) Lens FL 150 mm: 211132

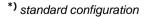
Lens FL 200 mm: 211133

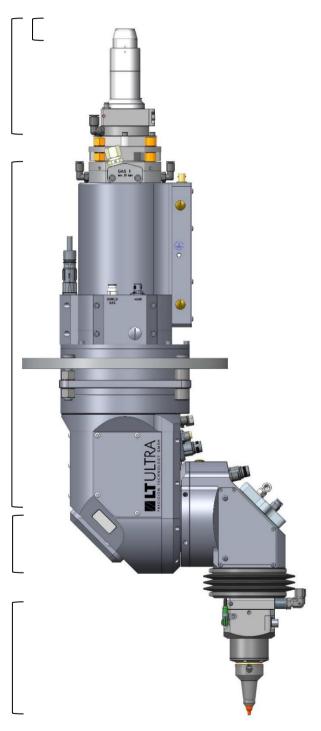
\*) Protection glass 6,35 mm: 211525

\*) Insulator M30x1 mm: 232279

Insulator 3 mm extended: 233211

distance sensor optional







# **6 INQUIRY TEMPLATE**

# Please send the completed sheet together with your inquiry to us.

Company:										
Contact Person / responsible for:										
	·									
Wished configuration	on:	Fiber	mount	Colli	Collimator FCU32			Focusing CHA32		
		QB	QD	80 mm	100 mm	I	120 mm	120 mm	150 mm	200 mm
	1.									
	2.									
Application:						"	<b>-</b>			
Focus shift range:	max. "focus +":					max. "focus –":				
	max. 10000 · .									
Laser:	Supp	olier / po	wer:	Wav	e lengt	length: BPP:				
Cooling water temperature:	MIN:				MAX:					
CNC:	Compliant To					Motor drive module:				
CNC.	Supplier:			Туре	Type:			O 230 O 420 Vac		
Distance sensor:	O no sensor O sens			nsor:	sor:					
Comments:										